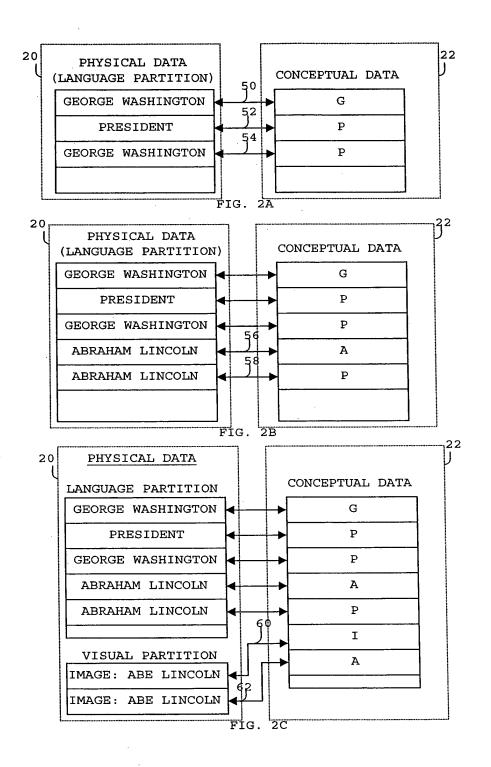


FIG. 1



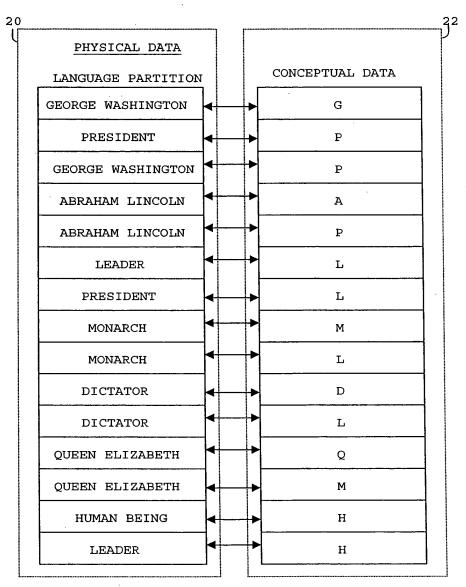
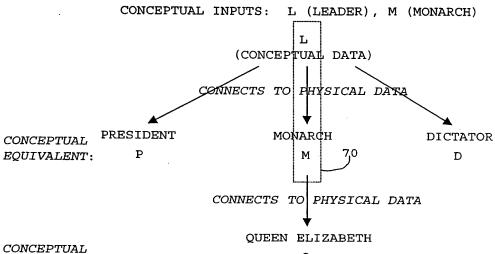
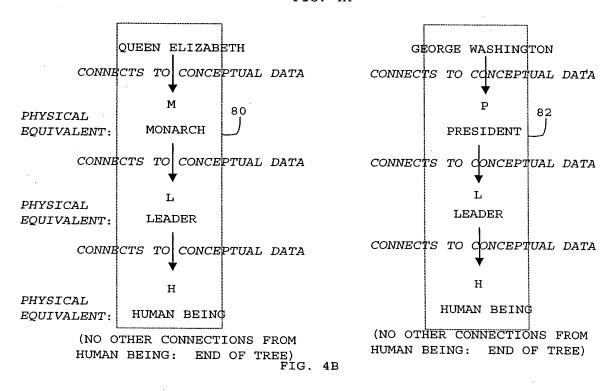


FIG. 3



EQUIVALENT:

(NO OTHER CONNECTIONS TO Q: END OF TREE) FIG. 4A



RETRIEVAL ALGORITHMS

REDUCTION	C < L
IMAGING	C>A, C>V, C>M, C>S
DEDUCTION	L < C
RECOGNITION	A <c, m<c,="" s<c<="" td="" v<c,=""></c,>
RECALL	C > L
CATEGORIZATION	R > C
REASONING	R1R2 < C1 ^ CN ^ C2

WHERE:

- R = REPRESENTATIONAL, OR PHYSICAL DATA OF ANY KIND;
- C = CONSCIOUSNESS, OR CONCEPTUAL DATA;
- L = LANGUAGE REPRESENTATIONAL/PHYSICAL DATA;
- A = AUDITORY REPRESENTATIONAL/PHYSICAL DATA;
- V = VISUAL REPRESENTATIONAL/PHYSICAL DATA;
- M = MOTION REPRESENTATIONAL/PHYSICAL DATA;
- S = SENSORY REPRESENTATIONAL/PHYSICAL DATA;
- R1, R2 ARE REPRESENTATIONAL ELEMENTS, AND C1, C2 ARE RESPECTIVE, CORRESPONDING CONCEPTUAL ELEMENTS; AND CN REPRESENTS MULTIPLE, UNKNOWN CONCEPTUAL ELEMENTS;

AND,

- < = SINGLE INPUT, POTENTIAL MULTIPLE OUTPUT;</pre>
- > = MULTIPLE INPUT, POTENTIAL MULTIPLE OUTPUT; and,
- ^ = INTERSECTION.

FIG. 5

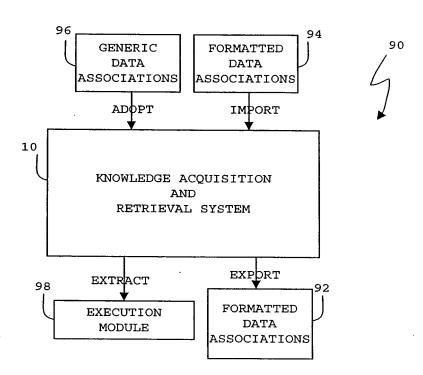


FIG. 6

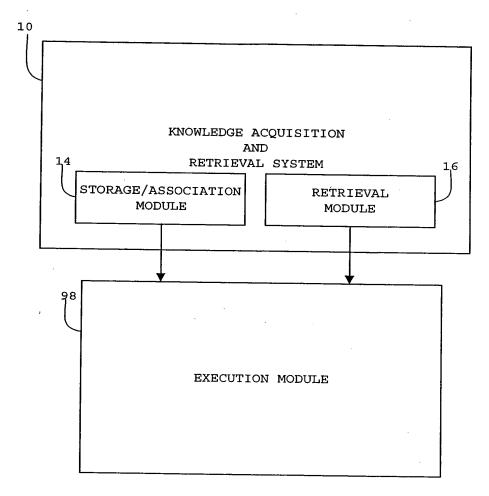


FIG. 7